

# Adversarial Network for edge detection

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- **Domain/Fields:** A type of neural network called the conditional generative adversarial network (cGAN) to address the edge detection problem. cGAN is an innovative framework to do the image synthesis task.
- **Issues :** Producing a high-quality edge map directly without further processing, to avoid further steps of non maximum-suppression
- **Problems** Most of the existing neural network-based systems use the convolutional network or its variant. They usually produce thick edges and the application of non-maximum- suppression to suppress the edge is necessary

- **The Proposed Method**

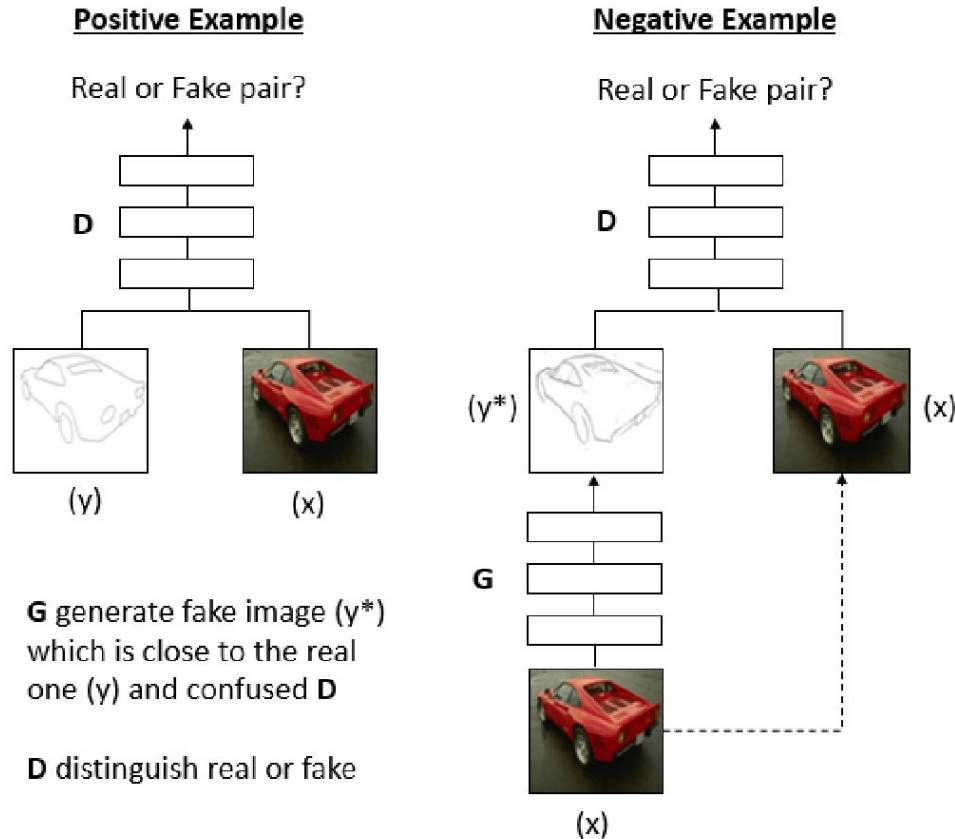
- This paper proposes an innovative edge detection algorithm based on generative adversarial network.
- This paper trains vanilla cGAN with dataset BSD500A CNN model is also proposed for the system to learn by using the generated input images.
- Since the original BSD500 dataset is a small one, it use augmentation to enlarge the size of the dataset method is implemented

- **The Contribution**

- The proposed method suggests one of approaches about regarding how we can use adversarial network for edge detection.
- Furthermore, cGAN can produce an image which is close to the real one

- GAN consists of two networks.
- One is the generator (G) and the other is the discriminator (D).
- After training, the generator (G) can produce images that are very close to the real images in the dataset.
- Define the images from the dataset as real images and the images produced by the generator are fake images.
- Objective of D is to distinguish whether the input image is real or not while the goal of G is to produce a fake image that looks like the real one.

GAN is hard to train, therefore alternative method called the conditional GAN (cGAN) to alleviate the problem.



- Directly predicting whether  $y$  or  $y^*$  is real or fake, our discriminator is used to predict whether a pair of  $(x; y^*)$ , or  $(x; y)$  is real pair or faker.[17]
- We use the generator to map input image from  $x$  to  $y$ .
- As seen in the image there is no noise  $z$  that is fed into the generator
- In vanilla GAN,  $G$  is the mapping noise  $z$  to one label image  $y$  in dataset.

## Vanilla GAN

$$\mathcal{L}_{GAN} = \mathbb{E}_{x \sim p_{data}(x)} [\log D(x)] \\ + \mathbb{E}_{z \sim p_z(z)} [1 - \log(D(G(z)))]$$

GAN is hard to be implemented because the first equation cannot provide sufficient weight gradient information for the generator to learn well.

## cGAN

$$\mathcal{L}_{cGAN} = \mathbb{E}_{(x,y) \sim p_{data}(x,y)} [\log D(x,y)] \\ + \mathbb{E}_{x \sim p_{data}(x)} [\log(1 - D(x, G(x)))]$$

Conditional GAN maps real image  $x$  in the dataset to  $y$

Generator targets to predict the edge map, i.e. there are only two classes in the map

Positive side = edges

Negative class = background

$$\mathcal{L}_1 = \begin{cases} \alpha \|G(x_i) - y_i\|, & \text{if } y_i > \eta \\ 0, & 0 < y_i \leq \eta \\ \beta \|G(x_i) - y_i\|, & \text{otherwise} \end{cases}$$

If the corresponding pixel value  $y_i$  in the label is greater than  $\eta$ , it is set to 0.5 in the program.

$\alpha$  is a hyper parameter that enlarges the L1 error of the pixel value  $x_i$  in the positive class of the predicted edge map.

If  $y_i$  equals to zero, it is a background pixel



- $\beta$  is applied as a hyper parameter to reduce the negative log-likelihood error.[23],[28]

$$\alpha = 1 + \frac{Y^-}{Y^+ + Y^-}$$
$$\beta = \frac{Y^+}{Y^+ + Y^-}$$

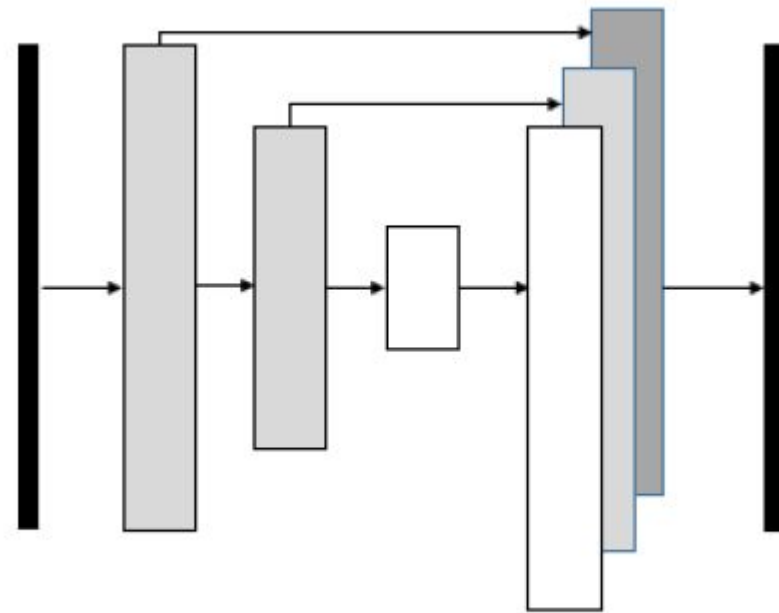
Objective loss function lambda which is the weight is set as 100.0

$$\mathcal{L}_{obj} = \arg \min_G \max_D [\mathcal{L}_{cGAN} + \lambda \mathcal{L}_1]$$

## Network Architecture

- It follows UNET[25] framework to design the generator.
- Decoder VGG16
- Only one neuron in the output layer

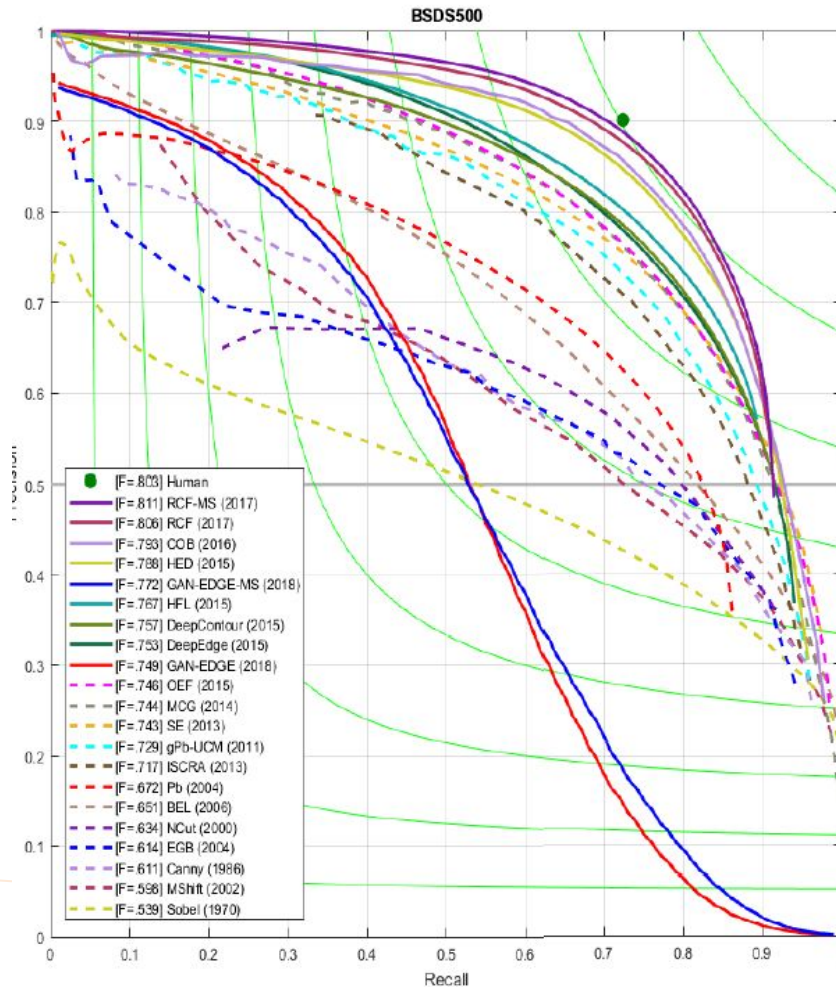
- Network Architecture



Modified UNET

Experiment:

- BSD500 dataset was used to evaluate our generator[2]
- 500 examples in the dataset, in which 200 for training, 200 for testing, and 100 for validation
- Augmentation was used rotating and scaling the images to increase the amount of dataset to a total of 28800



Both of our single-scale and multiscale approaches achieved good performances that were comparable to the other latest methods.

## Conclusion

- Achieved ODS and OIS scores on natural images that are comparable to the state-of-the-art methods.
- The model is computationally efficient.
- cGAN can produce an image which is close to the real one.
- Without using any pre-trained network parameters, the proposed method is still able to produce high quality edge images

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